

USER MANUAL

TBI 0310

11/2007

TRAUMATIC BRAIN INJURY DEVICE

Setting up the TBI 0310 Head Impactor

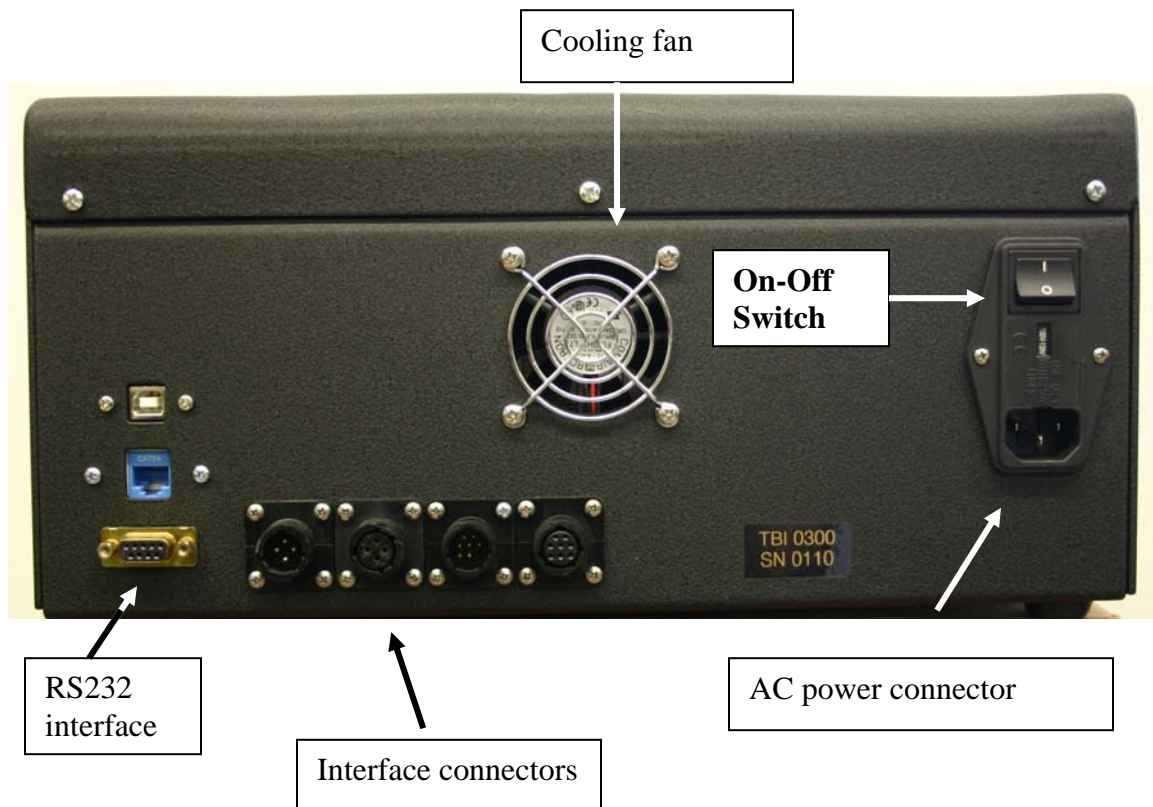
The TBI 0310 Head Impactor when fully assembled has the following components:

1. Control box
2. Impactor head stage assembly
3. Base plate for stereotaxic frame with stand post
4. Jun-Air compressed air pump
5. Flexible air hose with couplers (1)
6. Contact sensor
7. Calibration block
8. Rat impactor tip (5.0mm)
9. Mouse impactor tip (3.0mm)
10. Connection wire for contact sensor
11. AC power cord for control box
12. Quick release air coupler – female (1)
13. Hex wrench (set)
14. Spare impactor tip set screws (5)

Connecting the interface cables between control box and TBI 0310

- On the back of the control box there are four (4) black connectors, each with a different type of plug configuration.
- Match connectors with the same type of plug at the end of the wires from the TBI 0310 unit and tighten. Align the keying slot, insert the cable connector and turn the finger nut approximately $\frac{3}{4}$ turn.

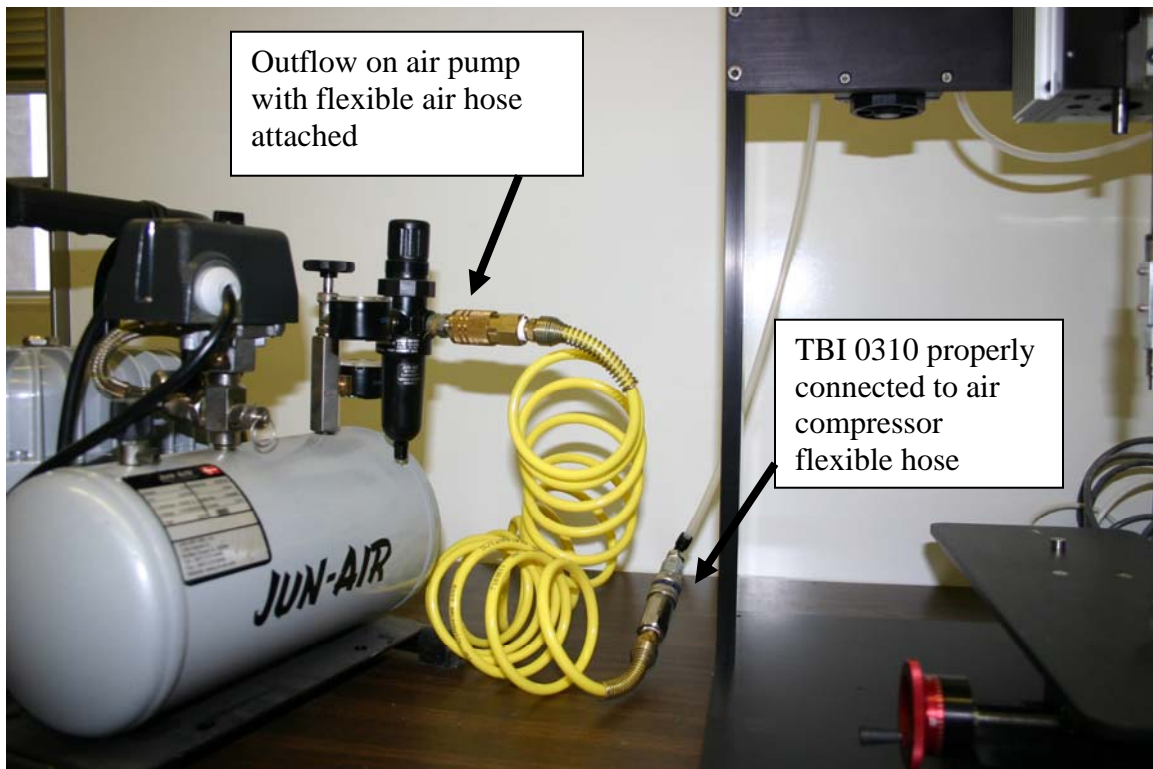
Attach the AC power cord to back of the control box



Connect the Jun-Air compressor to the TBI 0310

After unpacking the Jun-Air compressor and assembling according to manufacturers instructions, confirm that the compressor is functioning properly. Tank gage should indicate 90 to 110 PSI. Adjust the regulator for till outflow gauge shows **80 psi** of pressure.

1. Attach a female quick release air connector to the outflow connector of the air pump
2. A fully assembled flexible extension hose is supplied.
3. Connect one end of the air hose to the outflow connector on the air pump and the other end to the male quick release air connector on the TBI 0310
4. When properly assembled the units should appear as in figure below
5. Refer to Jun-Air user manual for proper pump maintenance (draining tank moisture and maintaining proper oil level is very important)



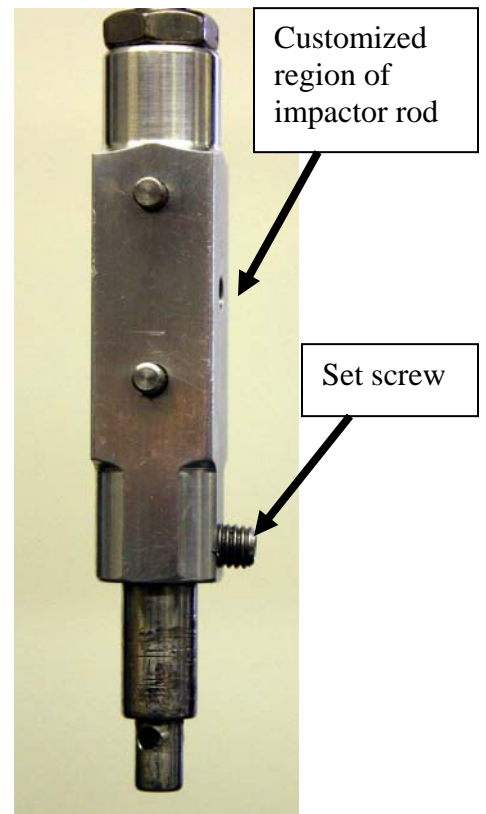
Attaching the impactor tips on the TBI 0310

There are two different size tips that accompany the impactor unit. The larger one has an external diameter of **5.0** mm and is used for large rodents such as adult rats. The small tip has an external diameter of **3.0** mm and can be used for smaller rodents such as very young rats and adult mice. Additional impactor tips can be custom made by contacting PSI.

Each tip has a standard size male threaded region that can be connected to the customized bottom section of the impactor rod that extends from the motorized head stage of the TBI 0310.

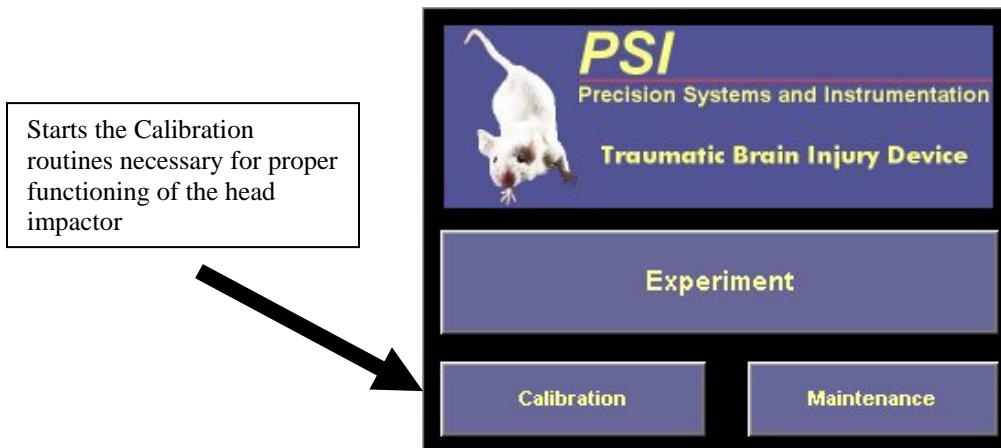
On one side of the customized section of the impactor rod there is a small set screw. When first delivered the set screw will not be installed. Extra set screws are provided with the accessories. Go ahead and install one. Using a hex wrench, partially unscrew this set screw which will enable the impactor tip to be connected to the bottom of the impactor rod. It is very important that the impactor tip be **securely hand tightened**. When tightening the impactor tip firmly hold the customized portion of the rod. Be extremely careful not to scratch the impactor rod portion that enters the impactor cylinder.

Once the impactor tip has been attached, use the hex wrench to tighten the set screw. This is important to assure that the tip does not become loose with repeated use of the impactor. **Check the tip for tightness often**. It can become loose after many hits. It is important not to **OVER TIGHTEN** the set screw. Tighten just enough to squeeze the plastic nub on the set screw into the thread of the impactor tip. Over tightening will ware out the plastic nub and can damage the threads on the impactor tip.

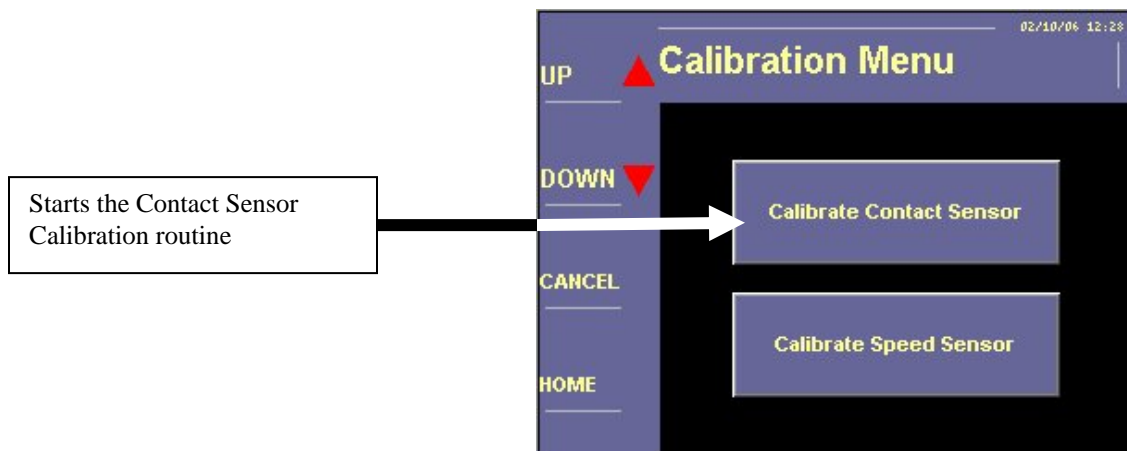


Calibrating the CONTACT SENSOR

- Prior to using the TBI Head Impactor for the first experiment it is extremely important to calibrate the CONTACT SENSOR
- This procedure informs the control unit what the distance is between the bottom of the impactor tip and the bottom of the CONTACT SENSOR
- This information is extremely important in order that the correct cortical deformation is carried out as desired by the investigator
- On the main menu screen on the control box press the “Calibration” button

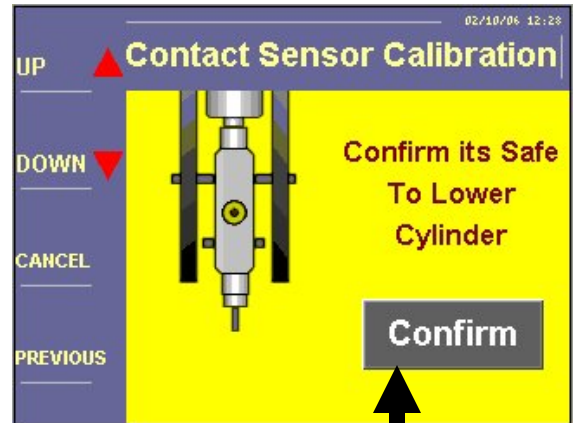


- The Calibration Menu will appear on the control box
- Press the Calibrate Contact Sensor button on the screen

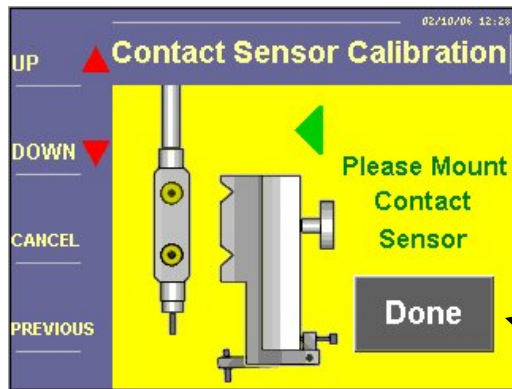


- This will activate the Contact Sensor Routine
- A new screen will appear asking for confirmation that it is safe to lower the impactor cylinder rod
- Remove all objects below the cylinder before pressing the Confirm button

- If all objects have been cleared from the beneath the cylinder press the Confirm button on the screen
- There may be a slight delay before the rod is lowered and a new screen appears on the control box
- Mount the contact sensor onto the head of the cylinder rod as indicated in the diagram

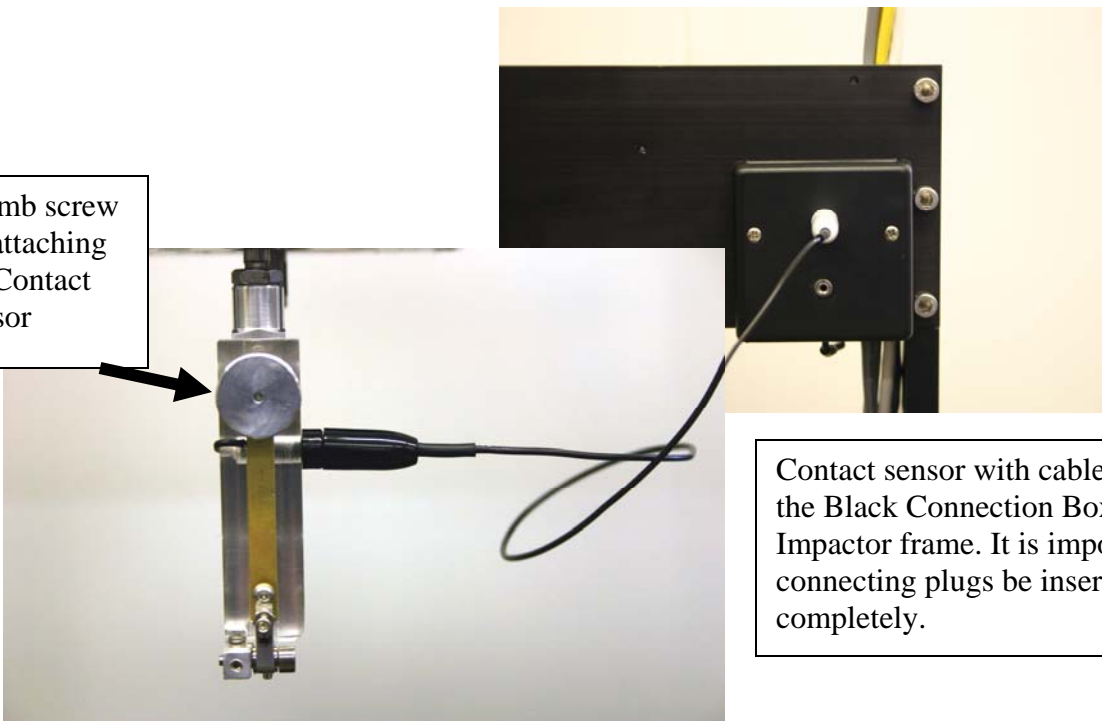


Pressing this button will automatically lower the rod within the cylinder



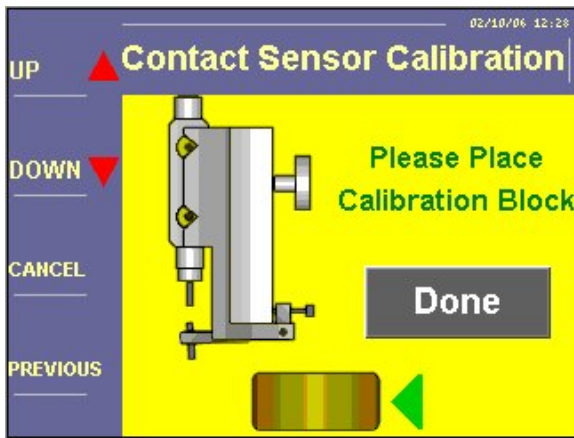
Press this button only after the Contact Sensor has been fully mounted. This requires that the Contact Sensor cable also be connected to the Contact Sensor and to the Black Connection Box on the Impactor frame.

Thumb screw for attaching the Contact Sensor



Contact sensor with cable connected to the Black Connection Box on the Impactor frame. It is important that the connecting plugs be inserted completely.

- There are small guide posts on the side of the cylinder rod head that match the notched indentations on the Contact Sensor as shown in the schematic diagram above
- **Be sure that the Contact Sensor is screwed tightly into the Cylinder rod head using the thumb screw**
- When the connections have been completed press the Done button on the control box screen
- A new screen on the control box will ask you to place the Calibration Block underneath the Contact Sensor
- If there is not enough room to fit the Calibration Block use the UP button on the Control box to raise the cylinder rod until there is enough room.



- Make sure there is approximately 1 cm space between the bottom of the Contact Sensor and the Calibration Block
- If more room is need use the UP arrow on the Control Box
- Press the Done button when everything is in place

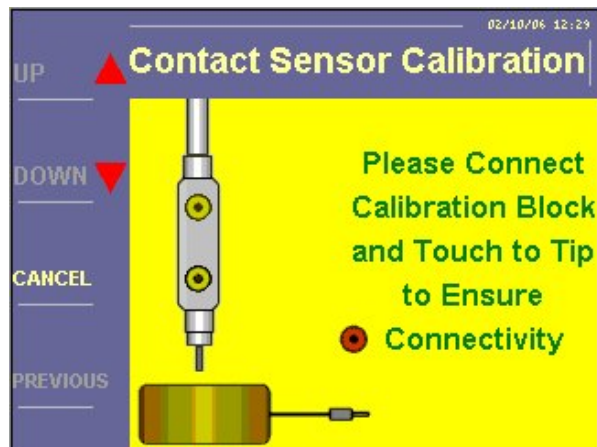
- A new screen will appear on the Control box asking for confirmation that all objects are in place
- Confirm that it is okay to Tare the Contact Sensor on the Calibration Box
- The motorized head stage will slowly move the Contact Sensor towards the Calibration Block



- Once the two meet the motorized head stage will move the Contact Sensor away from the Calibration Block
- A new screen will request that the Contact Sensor be removed from the head of the cylinder rod
- Also unplug the connecting wire from the Black Connection box



- Connect the wire attached to the Calibration Block to the Black Connection box on the Impactor frame
- Lift the Calibration Block so that it touches the bottom of the Impactor tip
- If the connection is good you will hear an audible beep



- Immediately after the audible beep the screen on the control box will change
- Place the Calibration Block immediately below the impactor tip in the position it was during the Tare procedure for the Contact Sensor
- When everything is in place press the green Proceed button on the control box screen



- The motorized stage will slowly lower the impactor tip towards the Calibration Block
- Once the tip touches the block the calibration procedure has been completed
- During this final step a new screen will appear on the control box

- **The calibration of the Contact Sensor will automatically be saved to the control box**



- This calibration procedure should be followed every time the Impactor tip is removed from the cylinder rod or when Impactor tips are changed (i.e. changing from rat to mouse tip)

Calibrating the SPEED SENSOR

- This procedure is necessary prior to the first time use of the instrument
- It is **NOT** necessary to calibrate the Speed Sensor before each experiment or when the tip is changed
- This calibration procedure should only be carried out if the instrument has not been used for an extended period of time (3 months) or if maintenance that affects the position of the sensors has been performed.
- On the Main Menu press the Calibration button



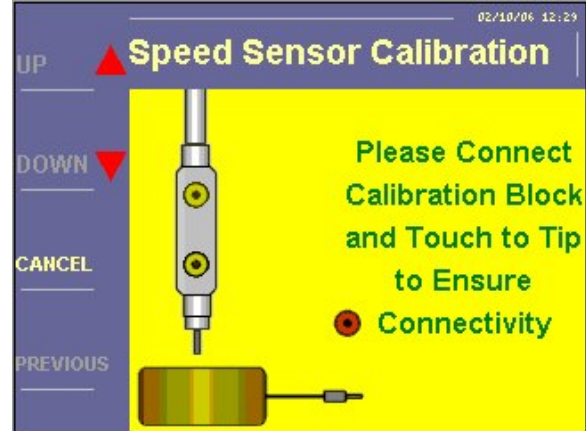
- Remove the Contact Sensor and the Calibration Block
- Confirm that it is okay to lower the cylinder rod
- The cylinder rod will extend downward from the cylinder



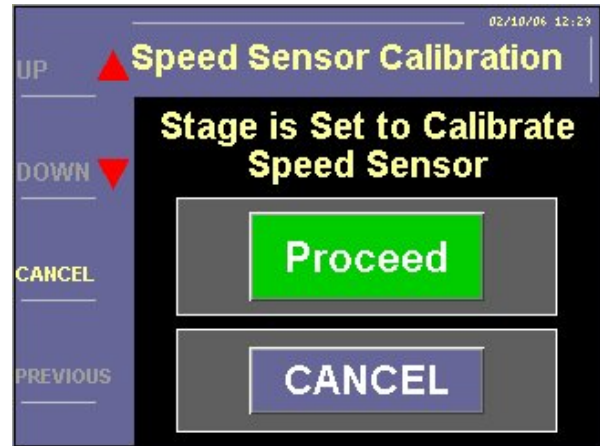
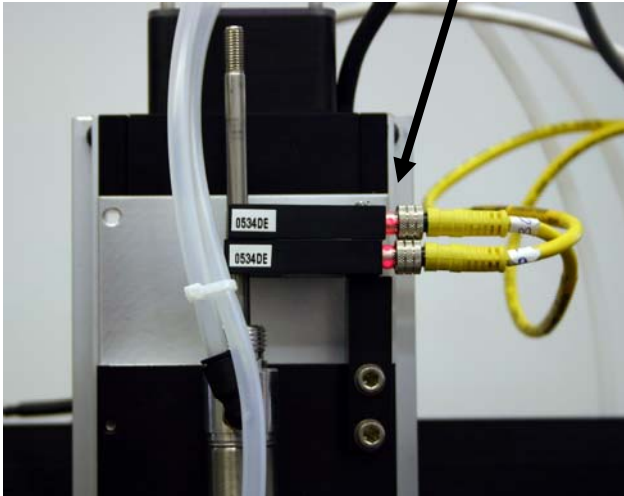
- Place the Calibration Block beneath the impactor tip
- If there is not enough room use the UP button on the control box to raise the impactor tip.



- Attach the wire connected to the Calibration Block to the Black Connection Box on the Impactor frame
- Raise the Calibration Block so that it touches the bottom of the Impactor tip
- If the contact is good there will be an audible beep and the screen on the control box will change
- Confirm that everything is in position for the Speed Sensor Calibration by pressing the green Proceed button on the control box screen



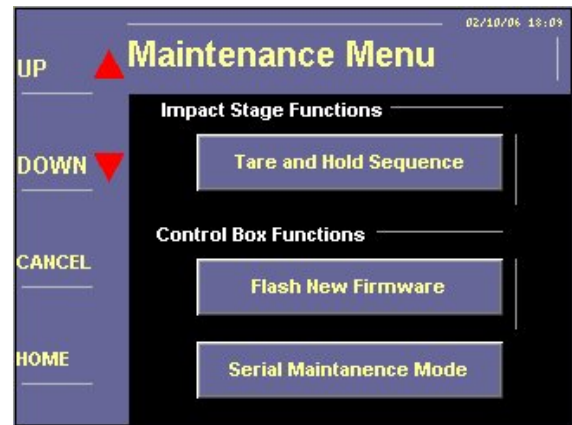
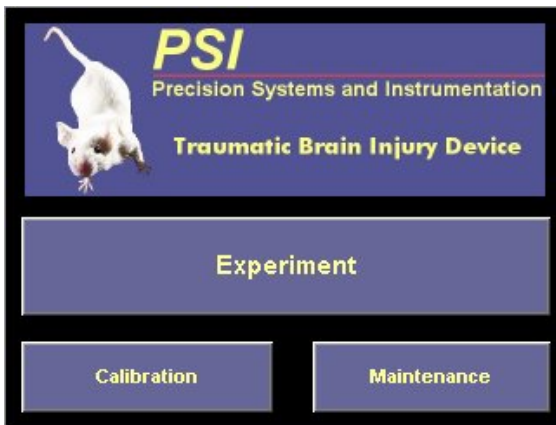
- During this procedure the top of the cylinder rod will move through a set of sensors on the top portion of the frame
- It is important that both red lights on these sensors are glowing red



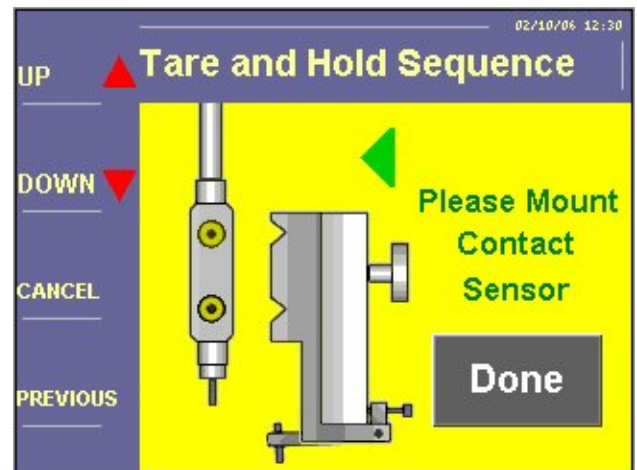
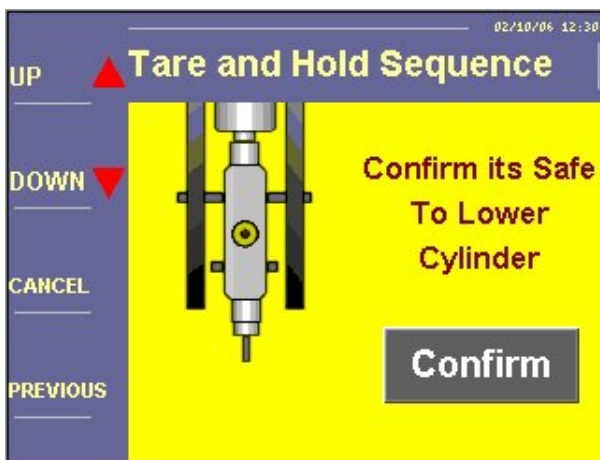
- It will take a little while for the top of the cylinder rod to go past both sets of sensors
- During this time you will see a red screen on the control box
- Once the calibration process is finished the cylinder will return to its previous position and the new calibration will be saved to the control unit
- The TBI 0310 Impactor is now calibrated and ready to use

Calibrating the Manual Switch of the Contact Sensor

- It extremely important that the amount of force used to trip the manual switch on the contact sensor is the same for all experiments in order for the injury to be consistent from experiment to experiment. This calibration procedure should be carried out every couple of months to assure consistency.
- In order to perform this calibration it is necessary to have a small digital scale (supplied by user) with a reading sensitivity of 0.1g

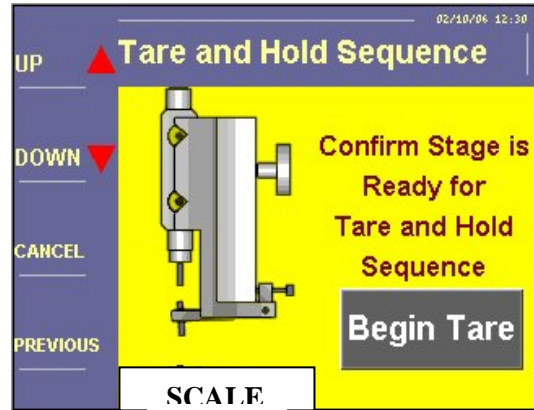
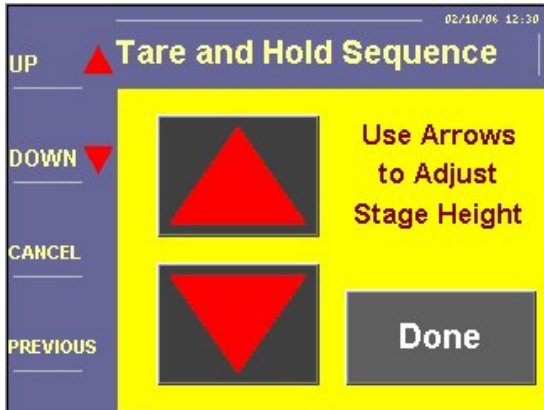


- From the main menu press the Maintenance button
- On the Maintenance screen press the Tare and Hold Sequence button.

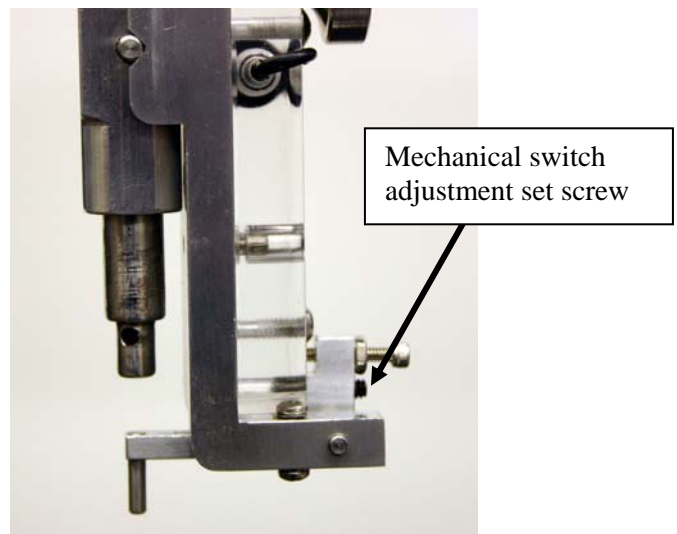


- Before pressing the confirm button be sure that the area beneath the cylinder is clear
- Once the cylinder rod has been extended mount the Contact Sensor. It is **not** necessary to connect the Contact Sensor to the black connection box on the frame
- Place the digital scale beneath the mounted Contact Sensor. If there is not enough room use the **UP** arrow on the control box to raise the motorized stage

- To begin the Tare and Hold Sequence use the **red arrow** to lower the contact sensor to approximately 1 cm above the middle of the scale's pan

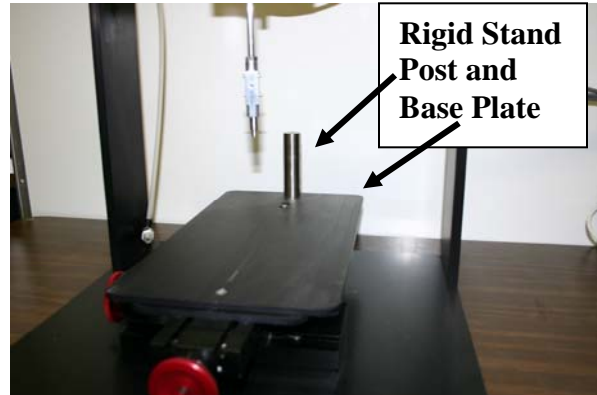


- Press the Done when the height has been properly adjusted
- With the digital scale perpendicular to the Contact Sensor and level press the Begin Tare button
- The motorized stage will lower the contact sensor onto the top of the scale and stop when enough grams of force trip the mechanical switch on the sensor
- Read the amount of grams on the scale. It should be in the range of 0.6 and 0.9 g
- If it is not you can adjust the mechanical switch by turning a small screw on the contact sensor
- Raise the contact sensor from the top of the scale with the arrows and unmount the sensor. A black set screw can be turned counter clockwise to increase the sensitivity (< 0.9g) and clockwise to decrease the sensitivity (> 0.6g)
- Remount the Contact Sensor and run the Tare and Hold Sequence again.
- Check and see if the grams necessary to trip the mechanical switch is between 0.6 and 0.9g. If not then raise the sensor and repeat the process.
- The injury device has now been completely calibrated for use.



Using the TBI 0310 Injury Device

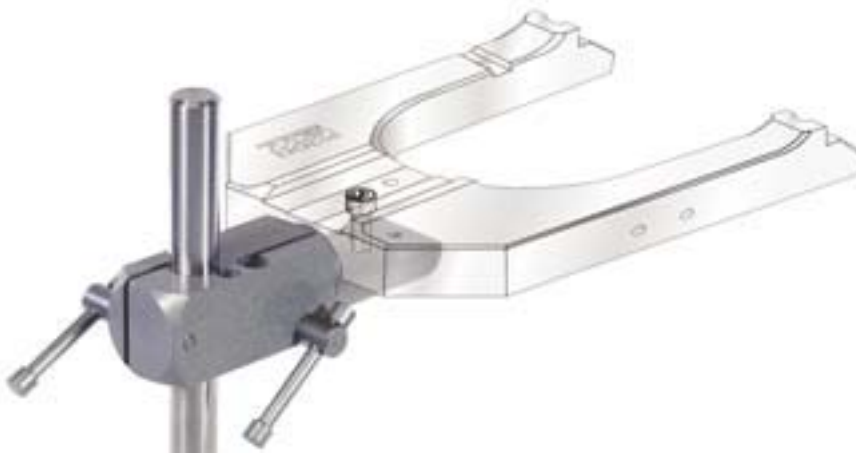
- In order to use the injury device a stereotaxic frame needs to be attached to the base plate
- On the base plate is a stand post that will accommodate a universal swivel that attaches to the front portion of the stereotaxic frame
- While different stereotaxic frames can be used with the device they must be free to rotate in a horizontal plane
- Rotating in this plane is necessary in order to position the animal so that the piston tip will contact the cortical surface in a perpendicular fashion
- David Kopf Instruments (Tujunga, CA) sells a universal clamp for some models of their stereotaxic frames. We recommend the universal clamp that is part of the #1725 clamp and stand post.



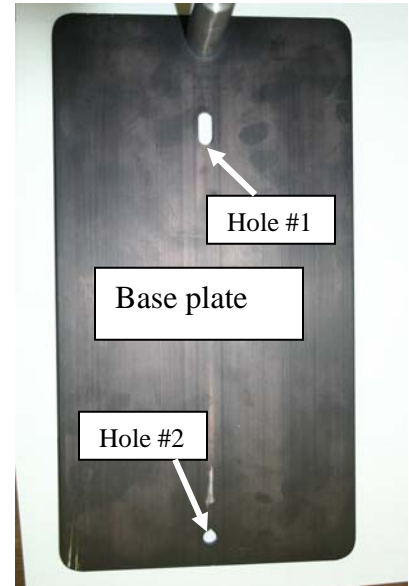
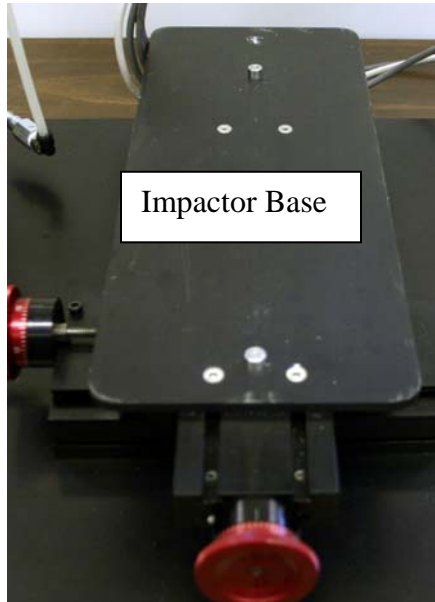
David Kopf #1725 universal clamp designed to attach a 1400 or 1700 stereotaxic frame to the TBI Impactor



- Smaller stereotaxic frames such as the Kopf 900 series can be adapted by purchasing the Kopf #925 swivel mount alone.

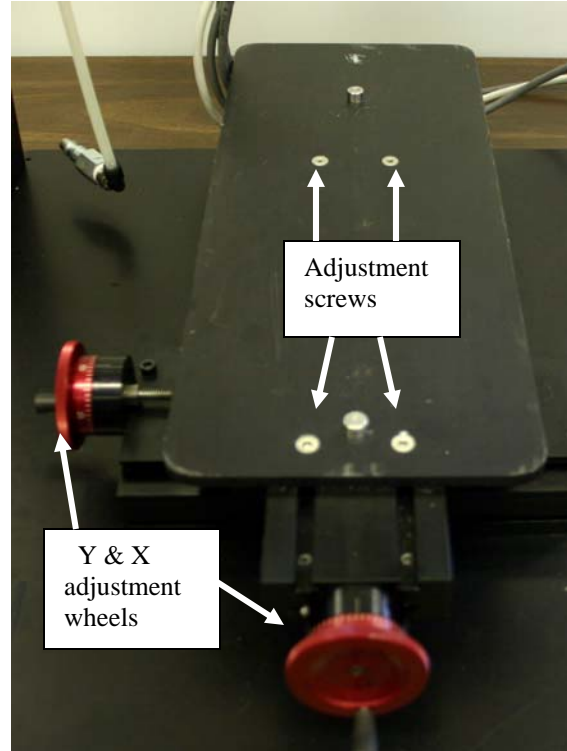


- The base plate used for mounting the stereotaxic frame has two holes that are used to mount it onto the base of the Impactor



- Mount the base plate onto the impactor base with the stereotaxic frame attached to the stand post
- Lower the impactor rod and tip and check to see if you can adjust it with the X and Y control wheels to travel in the full useful range for performing an impact on the animal of choice (rat or mouse)
- When the instrument is shipped, the Impactor Base is set at the factory to minimize the X axis for shipping purposes and may need to be adjusted especially for small rodents such as mice.
- There are a series of four screws on the Impactor Base that can be loosened with a hex wrench for this adjustment

- Loosen each of the four adjust screws just enough to easily slide the Impactor Base on the frame
- Slide the Impactor Base up or back to and tighten the adjustment screws
- Mount the Base plate with the stereotaxic frame and use the adjustment wheels to check the movement of the plate
- If necessary repeat the adjustment procedures above until you are satisfied with the X & Y movements
- Tighten the adjustment screws on the Base plate

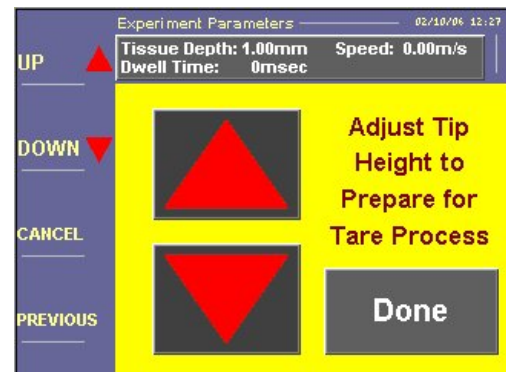


Performing an impact with TBI 0310

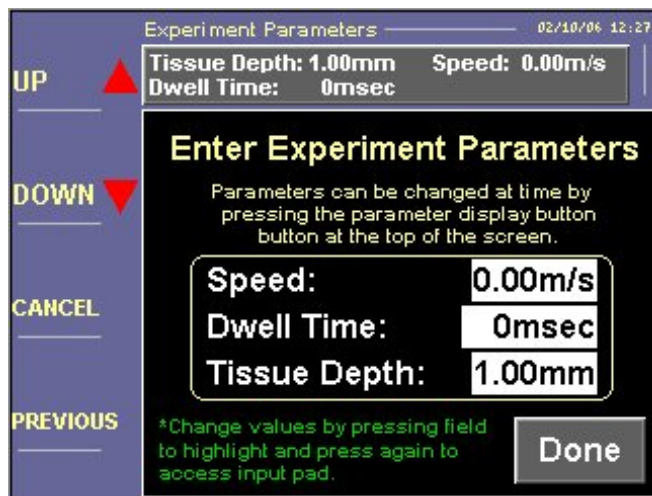
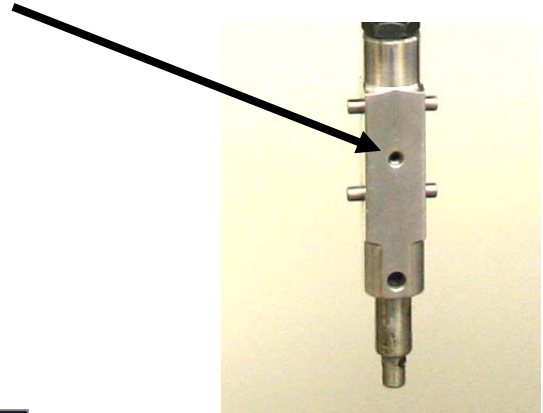
- Place the animal in the stereotaxic frame on the base of the impactor and be sure that the holes in the base plate line up with the holes on the base of the impactor
- It is important that that base plate fit flat on the impactor base. To assist in the mounting of the base plate one of the holes has an oblong shape.
- On the main screen of the control box press the Experiment button



- Confirm that it is safe to lower the impactor tip. We recommend that for the first time when lowering the tip that the animal and stereotaxic frame be moved to the side to make sure that there is enough room to lower the tip.
- Using the X & Y adjustment wheels on the base of the impactor, move the animal into position so that the impactor tip is directly above the area to be impacted
- It is important that the impactor tip be perpendicular to the area to be hit. This adjustment can be made by altering the horizontal angle of the stereotaxic frame. It is important to have the horizontal plane of the stereotaxic frame adjustable but not extremely loose.
- The tip of the impactor can be adjusted with the **red** up and down arrows on the control box
- This allows for a more precise determination that the area to be injured has been centered.

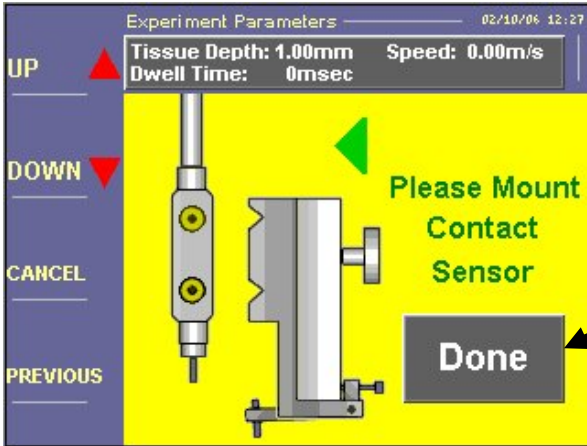


- Continue to adjust the base plate with the X & Y adjustment wheels to align the impactor tip
- The head of the impactor rod has a small threaded hole in the front that is used to attached the Contact sensor
- Make sure that the tip will fit completely into the craniotomy and not hit the sides
- Press the Done button
- It is time to enter the experiment parameters such as the Speed, Dwell Time, and Tissue Depth



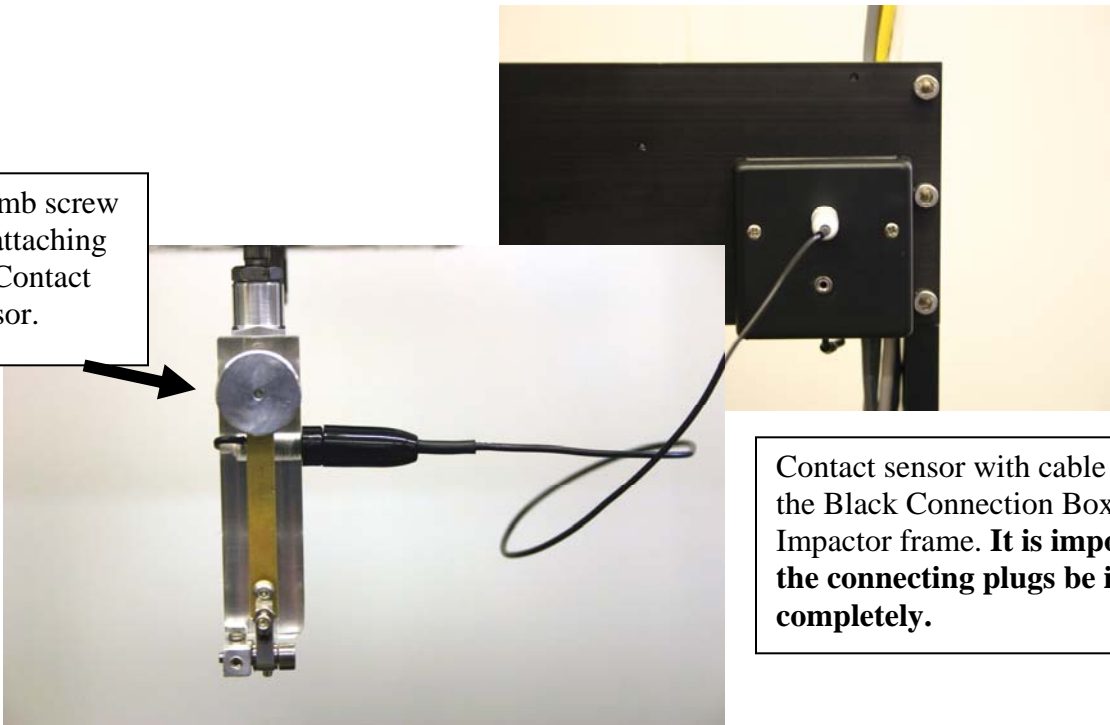
- The default values always show the first time the control box has been turned on. After the new experimental parameters have been entered they will remain that way until they are changed by the experimenter or the control box is turned off.
- To enter new parameters press twice on the highlighted field (e.g. 0.00m/s) that needs to be adjusted
- A small number pad will appear
- Press the numbers for the values to be entered (e.g. 3.50) and press enter
- Continue to change each of the parameters as necessary
- Dwell Time refers to the amount of time the impactor tip will remain in contact with the brain surface. The default value is 500 msec

- Mount the contact sensor onto the head of the cylinder rod as indicated in the diagram. Don't over tighten the thumb screw. Turn it enough that it just starts to get tight. Then go less than another 1/8th of a turn. The Contact sensor should be firmly attached at this point.



Press this button only after the Contact Sensor has been fully mounted. This requires that the Contact Sensor cable also be connected to the Contact Sensor and to the Black Connection Box on the Impactor frame.

Thumb screw for attaching the Contact Sensor.



Contact sensor with cable connected to the Black Connection Box on the Impactor frame. **It is important that the connecting plugs be inserted completely.**

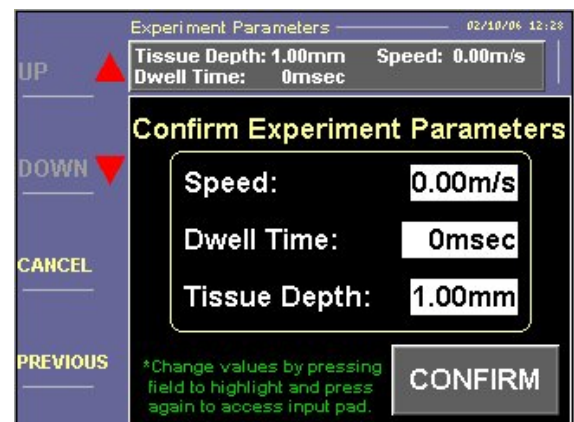
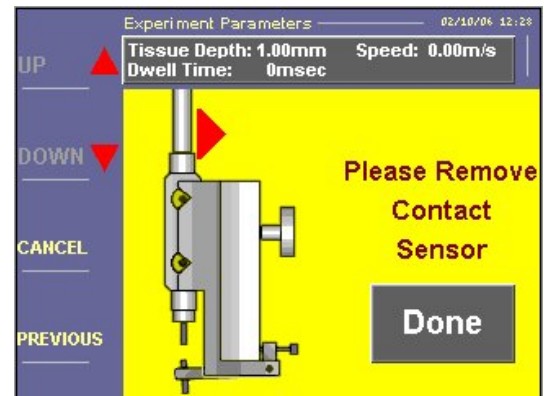
- It is very important that the head of the Impactor tip and mounted Contact Sensor do not rotate during this procedure

- **If the Contact Sensor is not mounted correctly or the wire to the black Connection box on the impactor frame is not attached, the Begin Tare prompt will not appear**
- If this happens be sure that the cable attaches to both the Connection box and the Contact Sensor
- The control panel will prompt to begin the Tare process. Press the Begin Tare button



- The motorized head will begin to lower the Contact Sensor towards the exposed surface

- This process will proceed slowly to assure that the correct distance to the exposed region is calculated by the control box
- It is recommended that the investigator watch to be sure that the contact sensor touches the exposed brain surface and not bone during this process.
- Once the surface has been contacted the motorized head will automatically raise the contact sensor so it can be removed
- Remove the Contact Sensor by unscrewing the thumb screw and disconnecting the wire to the black Connection box
- When finished with this task press Done
- The software will again ask to confirm that the injury parameters are correct. If not they can be altered again at this time



- If the parameters are correct press the CONFIRM button

- Once the experiment parameters have been set and confirmed the instrument will position the motorized head and impact sensor for the injury
- Press the Confirm button to indicate that this process can be initiated

**Positioning Tip
for Impact
Please Wait...**

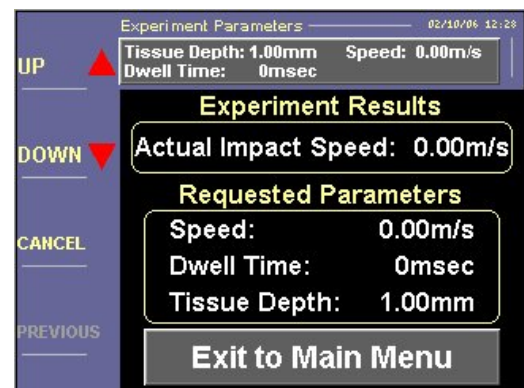


- During the positioning movement the control panel will display a warning sign
- It is important to inspect the surgical field to be sure that nothing can obstruct the impactor rod and tip from performing a complete impact
- If something does not look correct at this time the impact sequence can be aborted by pressing the CANCEL button on the control panel
- If everything appears to be okay then press the red **IMPACT** button

**IMPACT
In Progress
Stand Clear...**



- There will be a short delay followed by two audible beeps indicating that the impactor rod and tip will perform an impact
- After the impact cycle has been completed the control panel will display results from that particular impact
- The actual impact speed will be displayed



- To perform another experiment press the Exit to Main Menu button